Session 5 Mobile Robot Platform

Mobile Robot Platform

What capability can robot platform provide?

Mobility

Sensory Perception

Advanced Computer Vision

SLAM

Speech Recognition & Synthesis

Computation



Cherokey

特点:4轮越野版,自带电机驱动和电源管理, 只需要主控和传感器就可以玩

可以无需romeo,用 户可以使用自己的主控 系统



Devastator

特点:履带驱动版本

推荐使用Romeo BLE



HCR

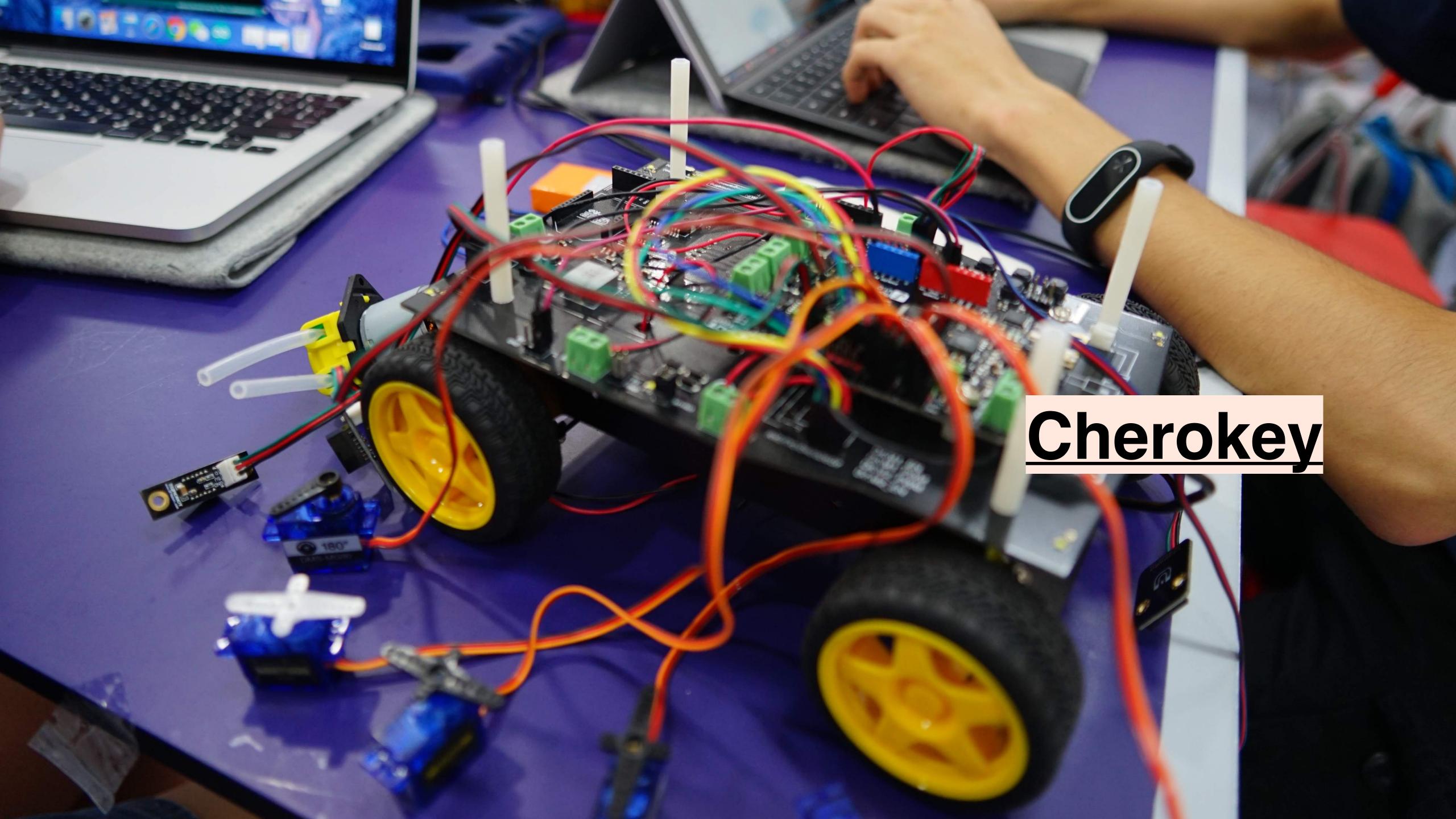
特点:针对专业用户,支持高达20多种传感器,能支持Kinect



Intel HERO

特点:高性能计算,提供多种接口,ROS界面、SLAM、Intel RealSense 计算机视觉能力、可视化编程接口



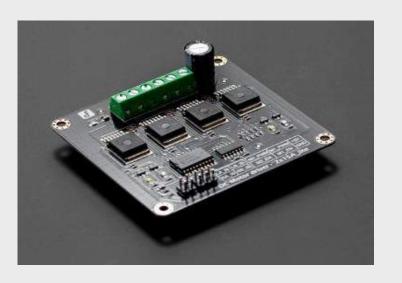


Cherokey

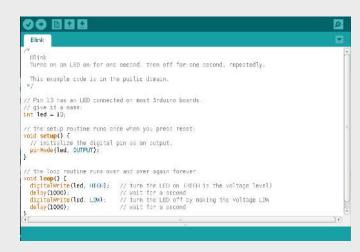
225mm*174mm*112mm 840g



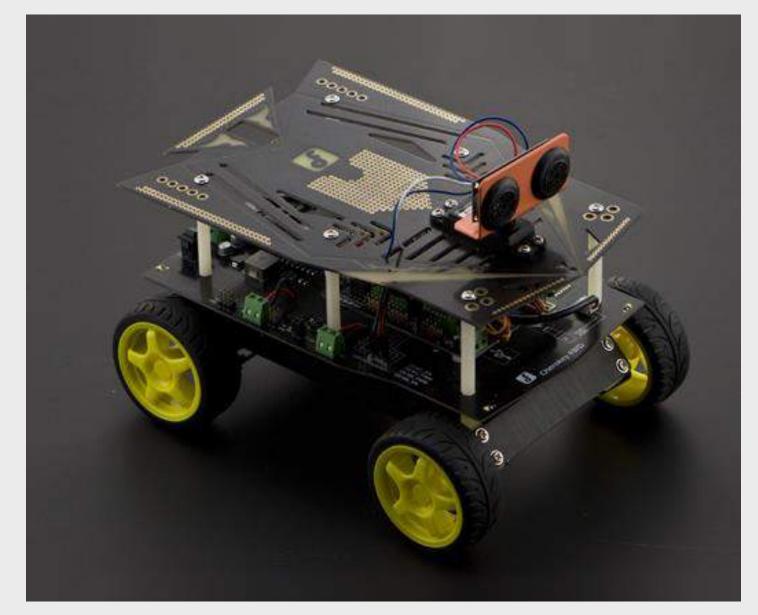
Micro-controller



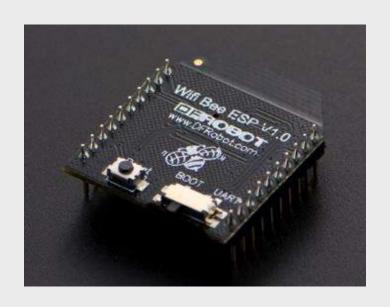
Motor Drive



Programming



Structure and Motor



Communication

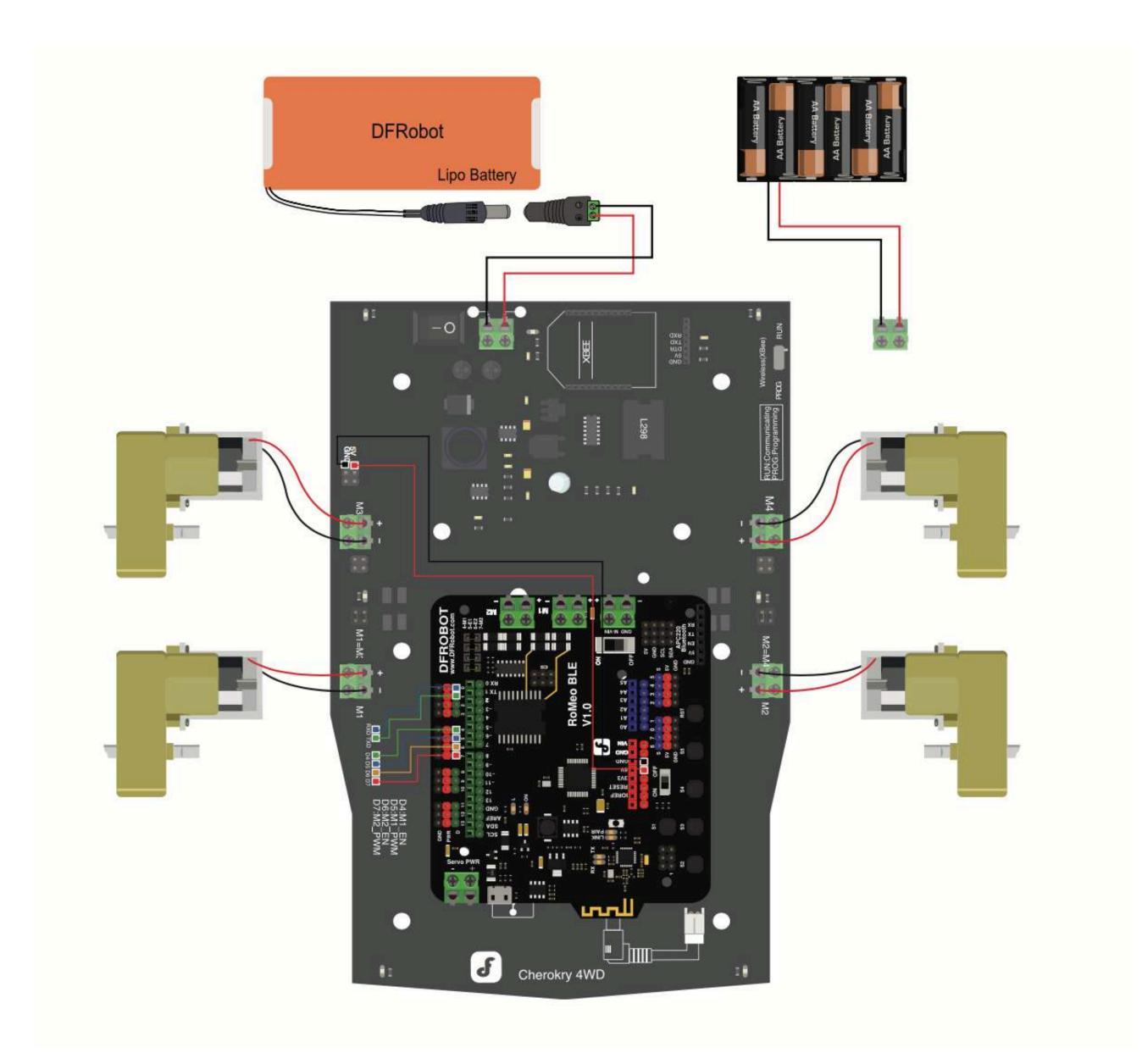


Sensor

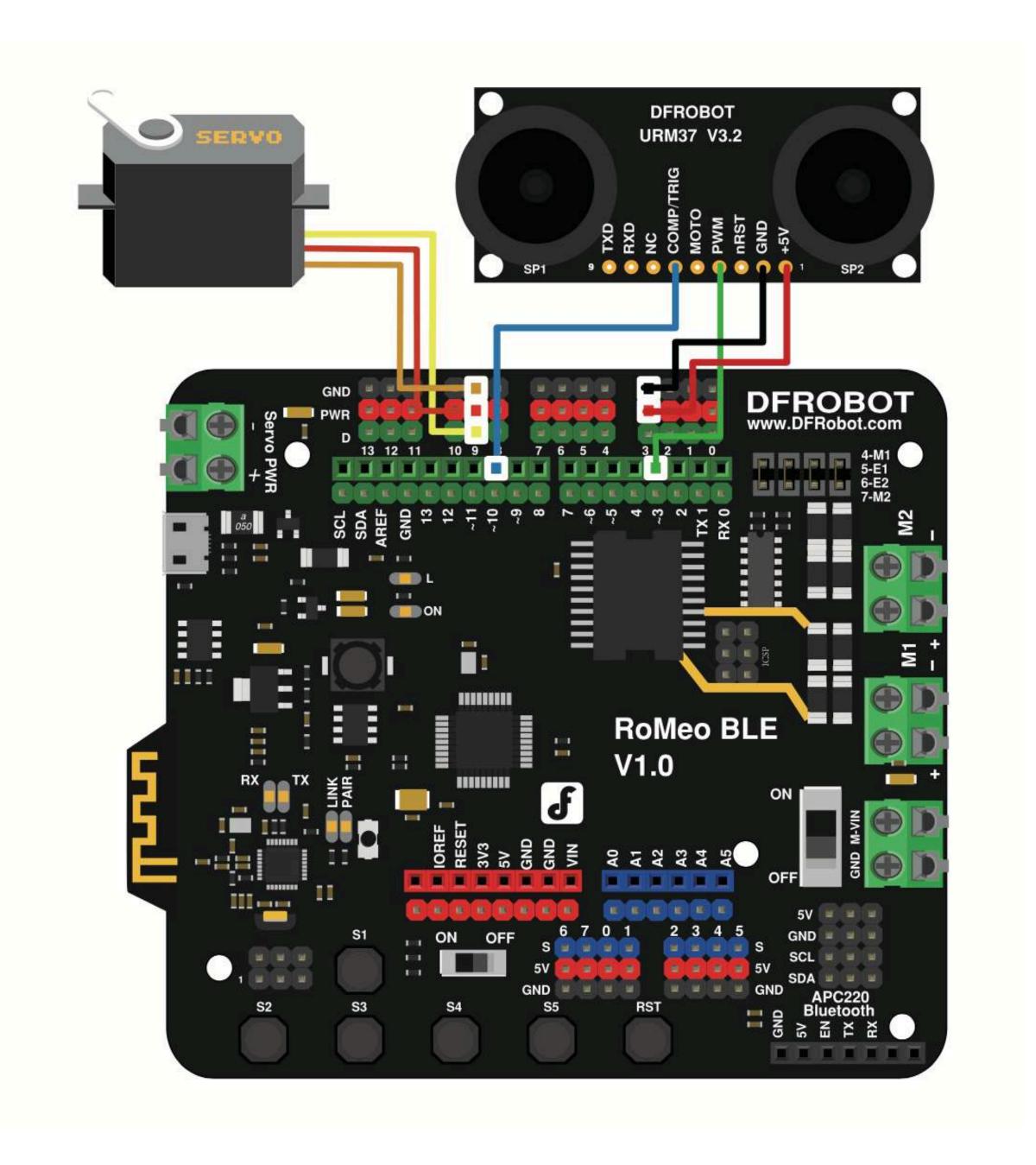


Power

Cherokey



Cherokey



Cherokey

Programmable Mobility

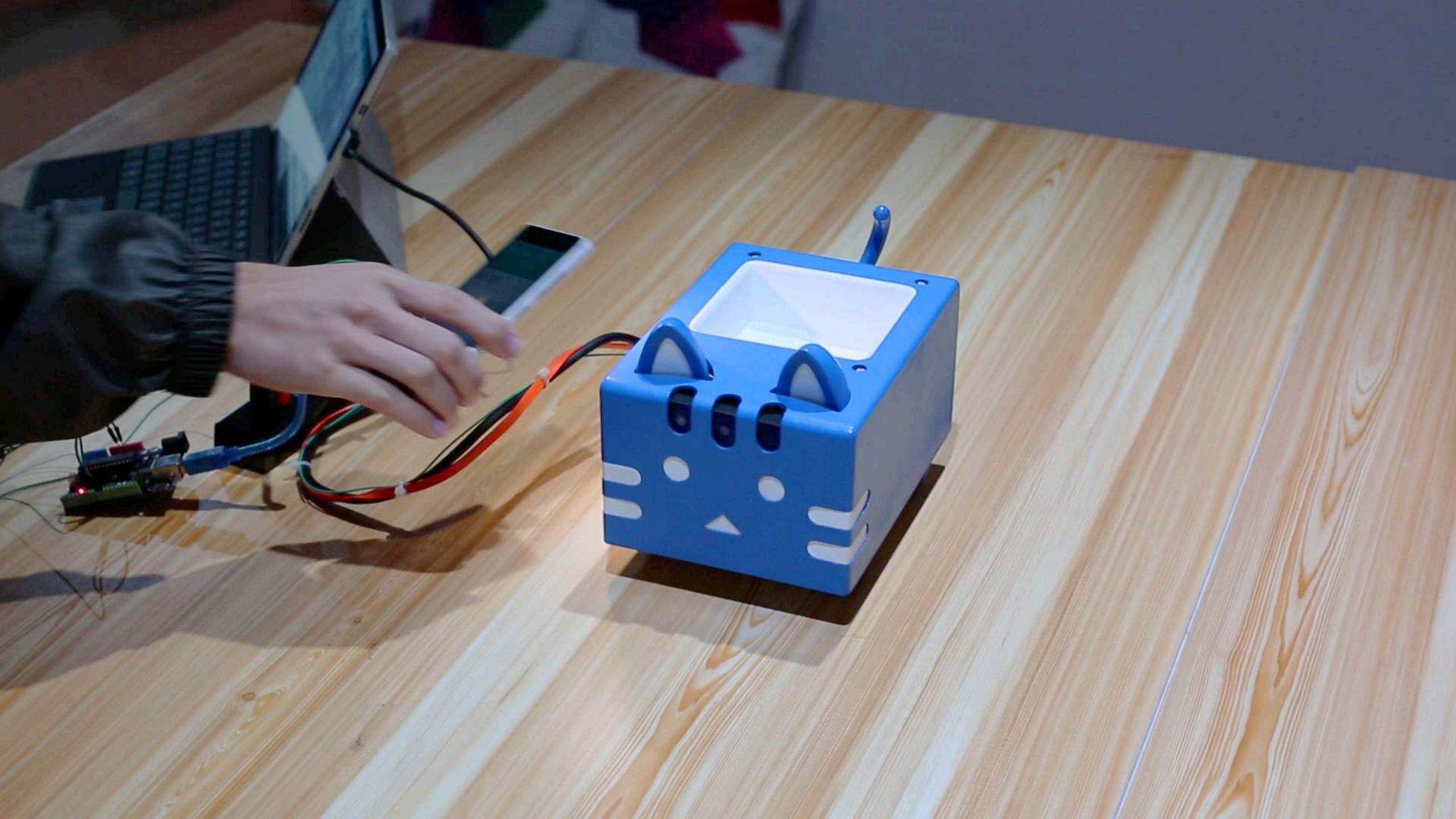
User has the ability to control the speed and direction of the four motors built in Cherokey, which can accordingly come into different mobility patterns.

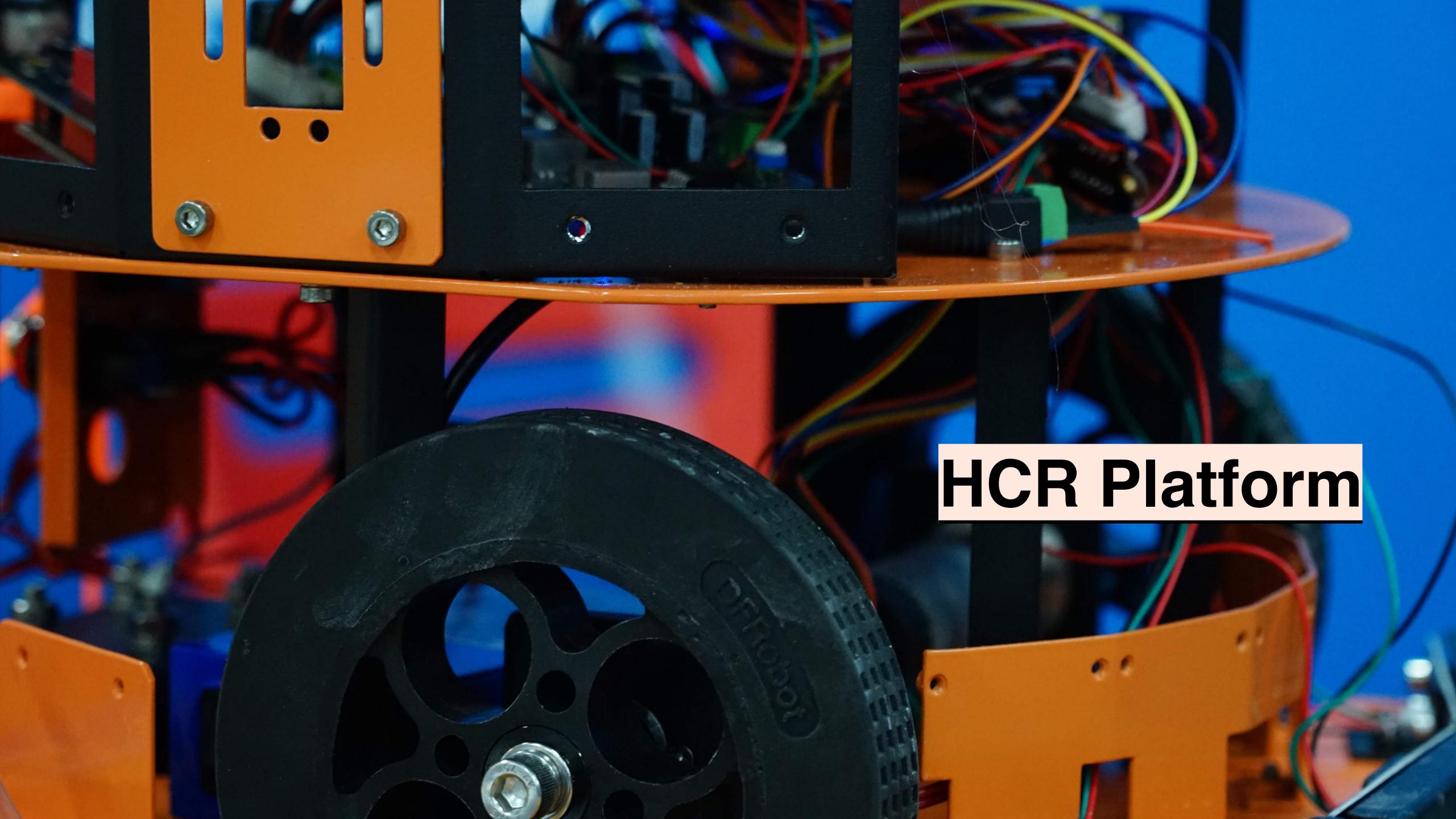
move forward

move backward

stop

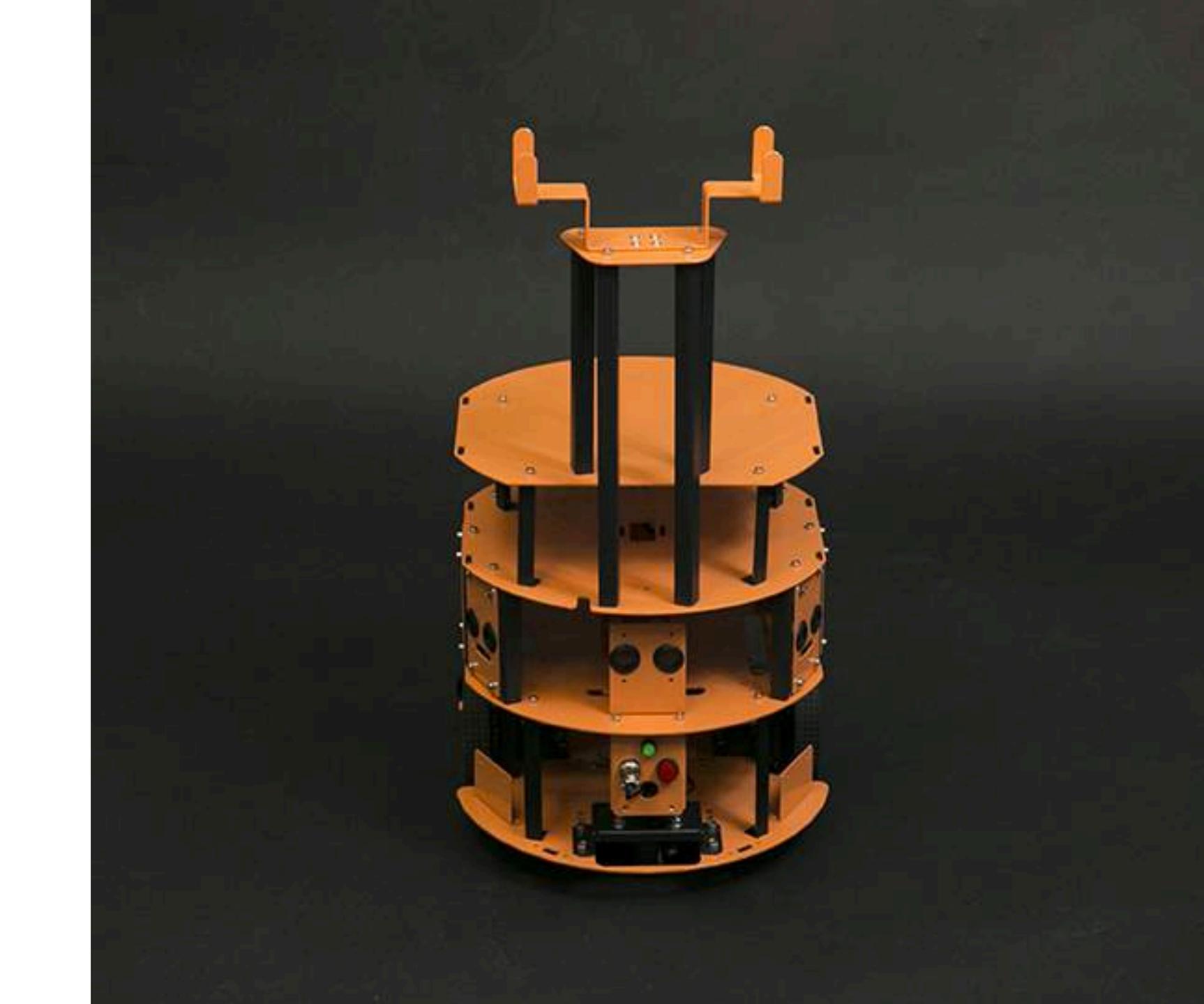
turn to one direction

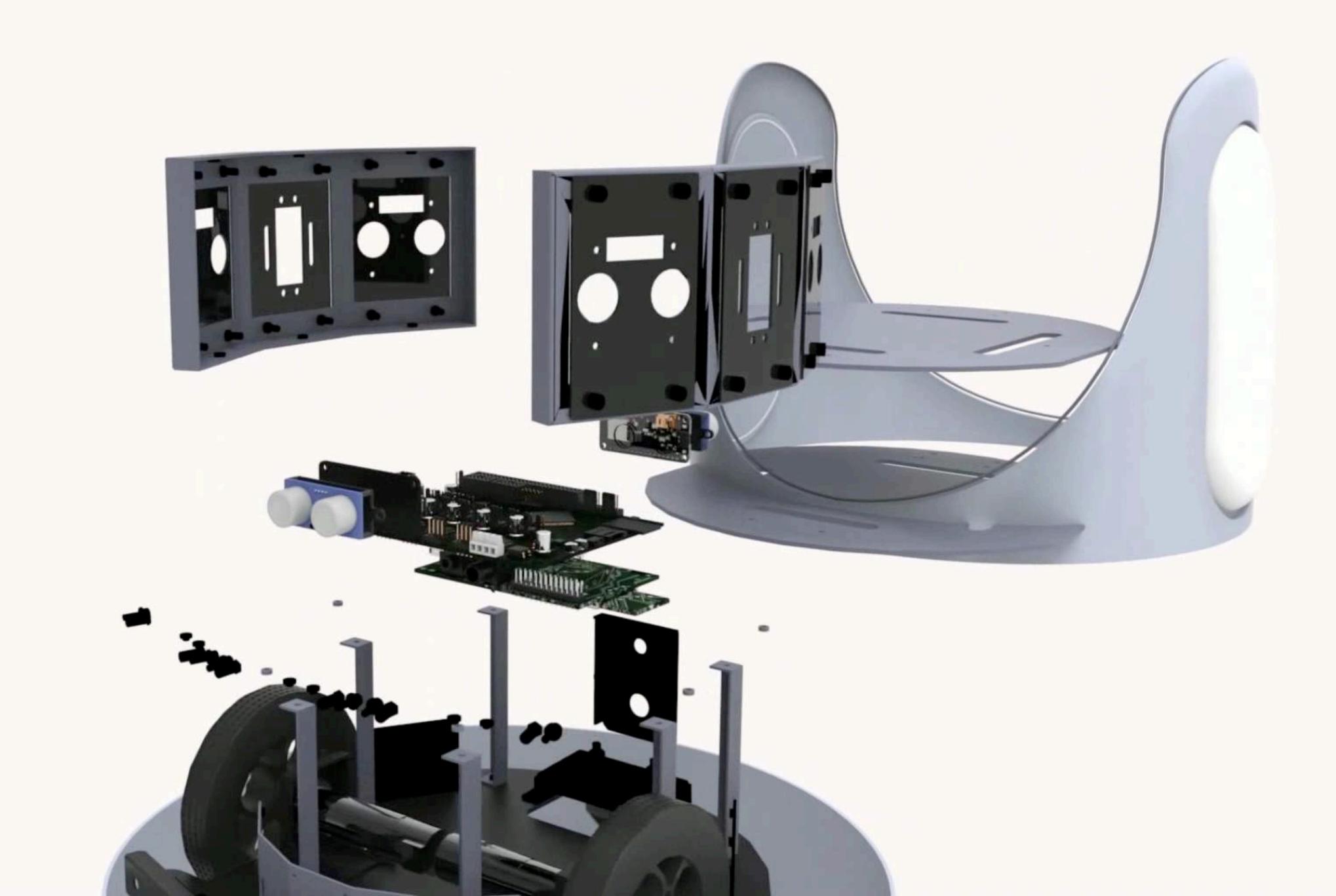




HCR

33 x 33 x 65 cm three layers two wheels multi-sensors built in





HCR

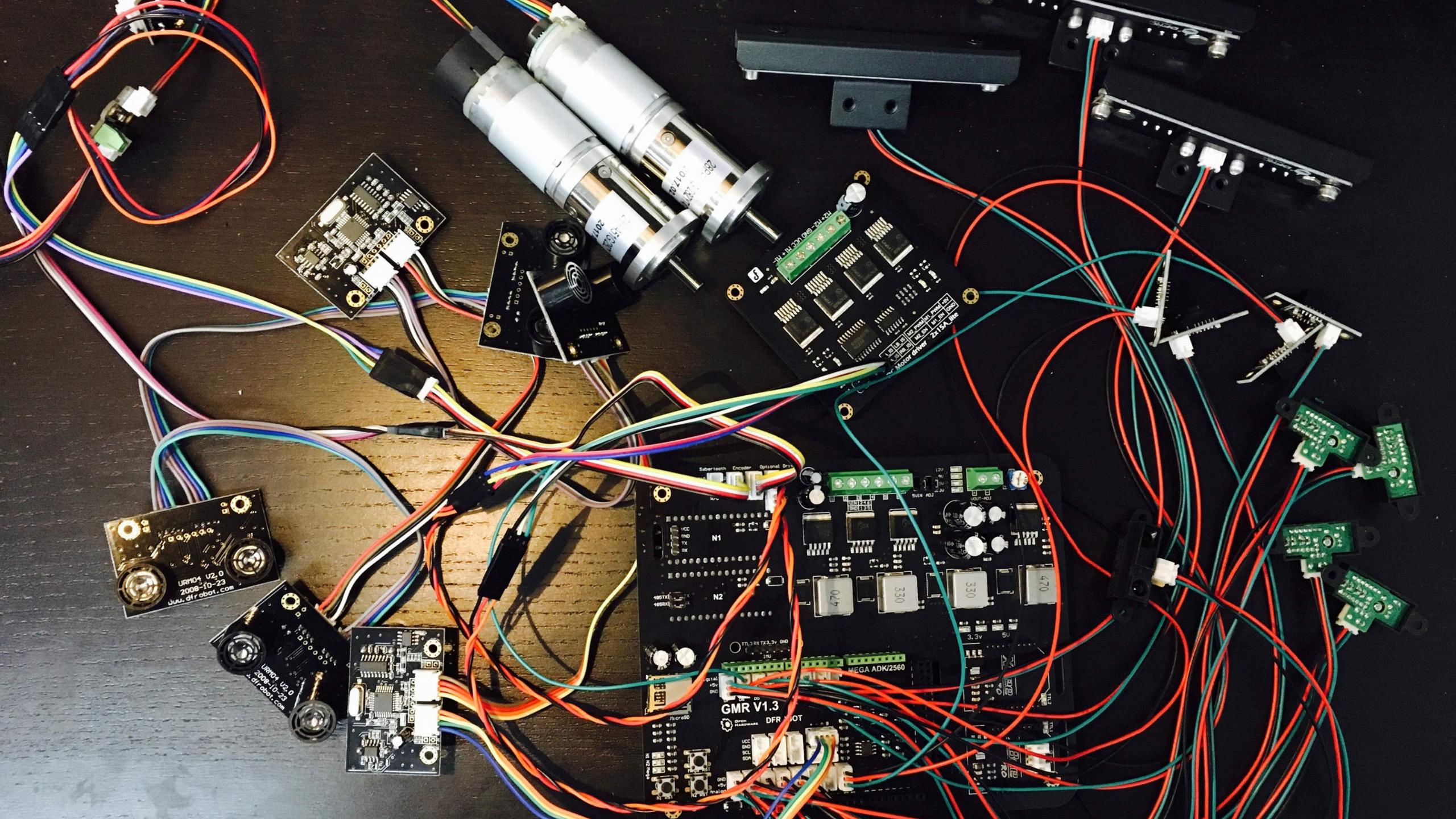
Specification

Sensor

URMO4 可级联超声波传感器 红外距离传感器 红外防跌落传感器 碰撞传感器 **Drive**

DFRduino Nano 3.0 15A双路电机驱动 Microcontroller

Mega2560 Arduino主控 GMR 机器人扩展板

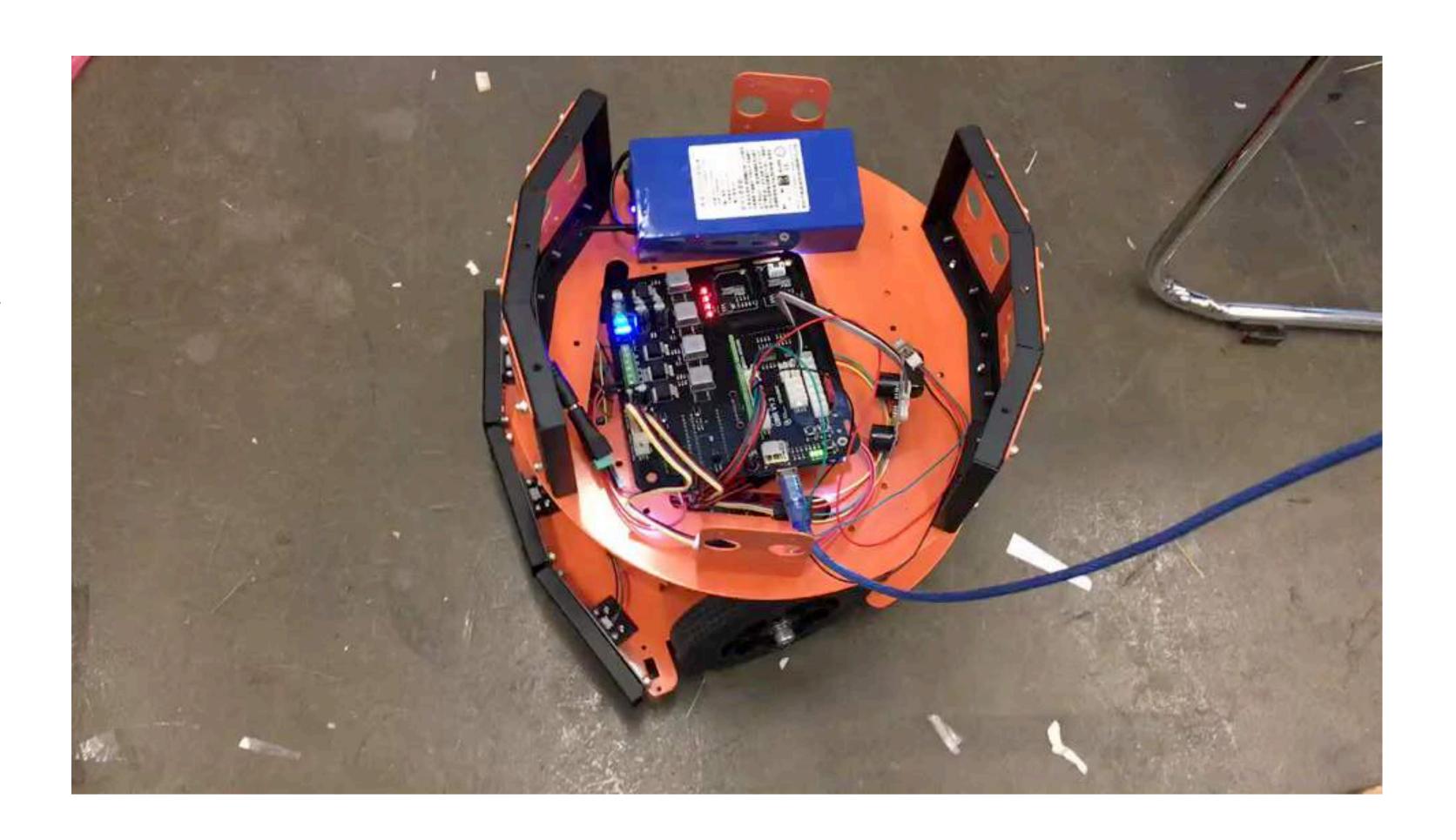


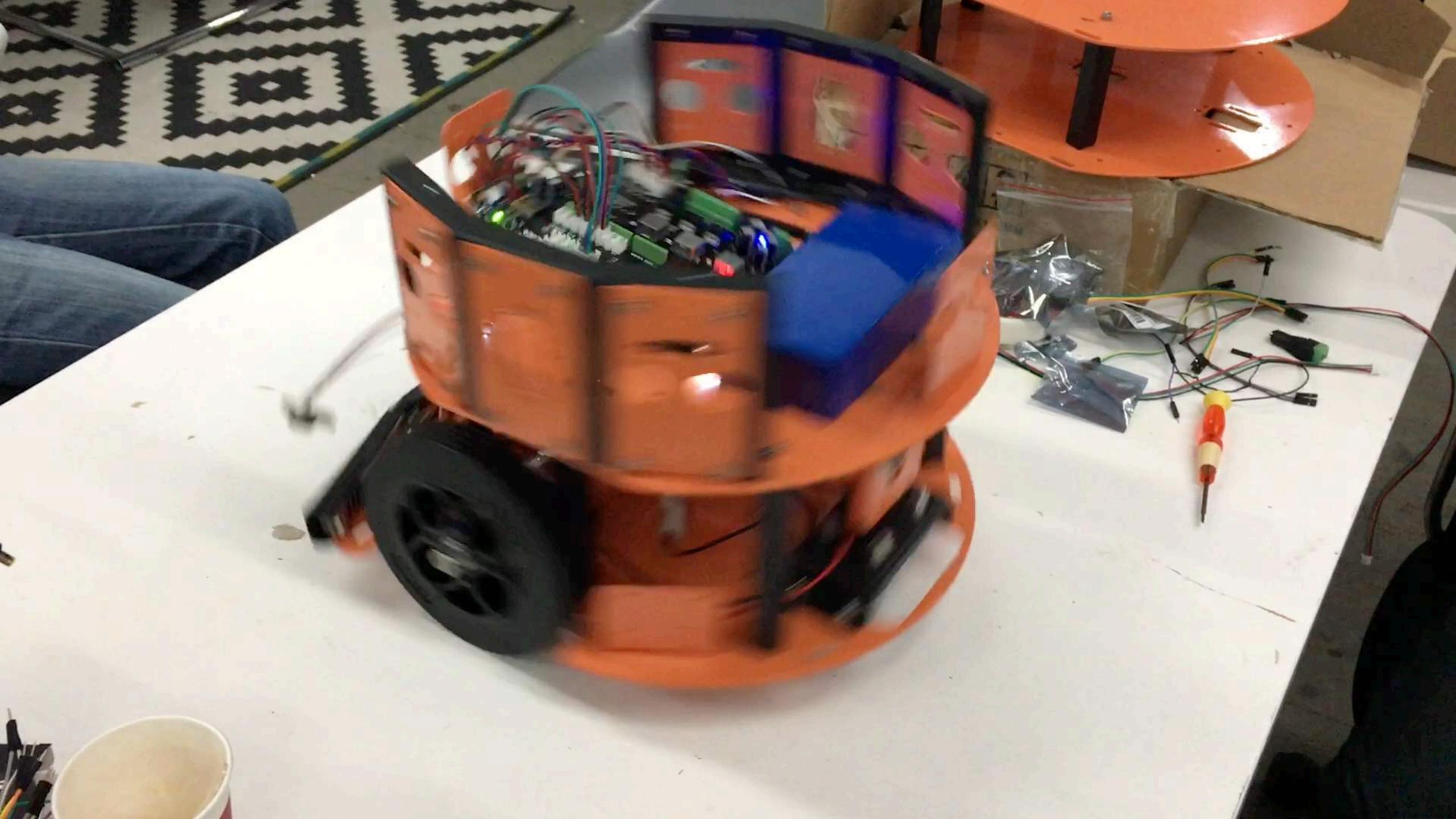
HCR

Programmable Mobility

User has the ability to control the speed and direction of the four motors built in Cherokey, which can accordingly come into different mobility patterns.

move forward
move backward
stop
turn to one direction







HERO

